

Sensor networks for real-time services

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Future networks

Cyber-World interacts with Real-World in Everyplace



Goals of this talk

- Give an understanding what embedded, ad hoc, sensor networks are good for, what their intended application areas are
- Discuss about main challenges in wireless sensor network applications
 - real-time constraints
- Propose possible approaches
 - Beacon scheduling algorithm
 - Sensor planning scheme

What are embedded systems?

- Computing system embedded in a larger system
 - Provide computing for a system with special purpose (cf. general purpose computing)
 - Computing itself is hidden from the user
 - computing is not the ultimate goal
 - computing serves for real mission (ECU of cars)
 - Usually perform static tasks - predetermined
 - Usually small to be embedded
 - Battery operated sometimes
 - Usually have “real-time” constraints

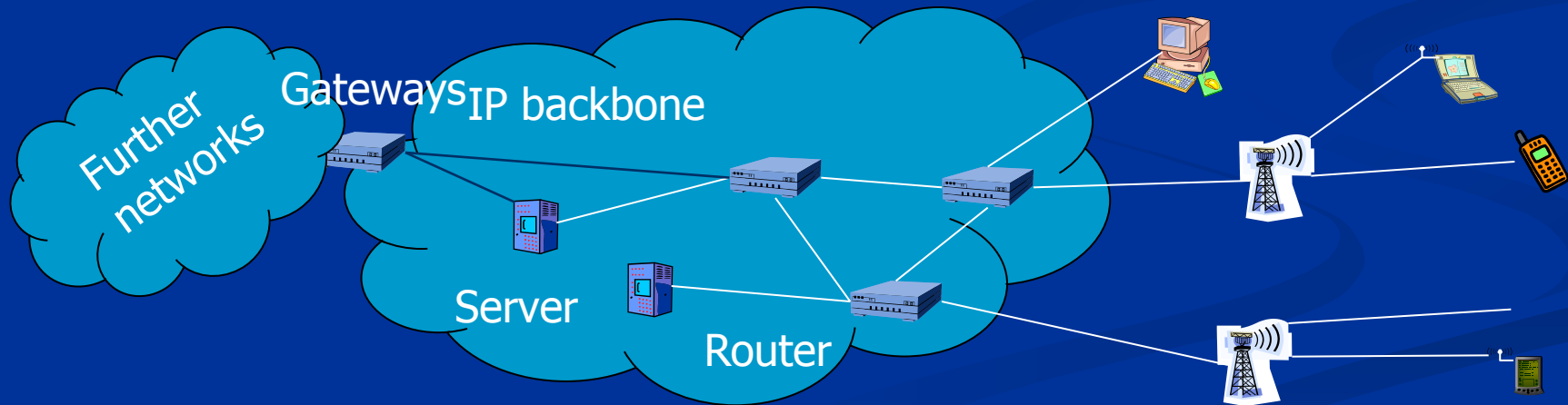
Possible applications for embedded systems

- Let's take a look at “examples”
 - Cell phones, PDAs
 - Digital cameras
 - Microwave ovens
 - Factory process control
 - Radar systems
 - Avionics



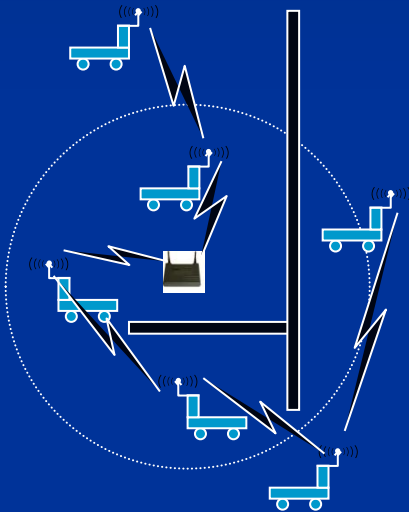
Infrastructure-based wireless networks

- Typical wireless network: Based on infrastructure
 - E.g., GSM, UMTS, ...
 - Base stations connected to a wired backbone network
 - Mobile entities communicate wirelessly to these base stations
 - Traffic between different mobile entities is relayed by base stations and wired backbone
 - Mobility is supported by switching from one base station to another
 - Backbone infrastructure required for administrative tasks

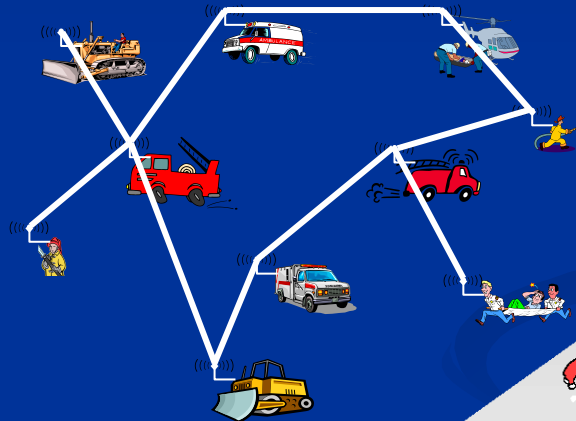


Possible applications for infrastructure-free networks

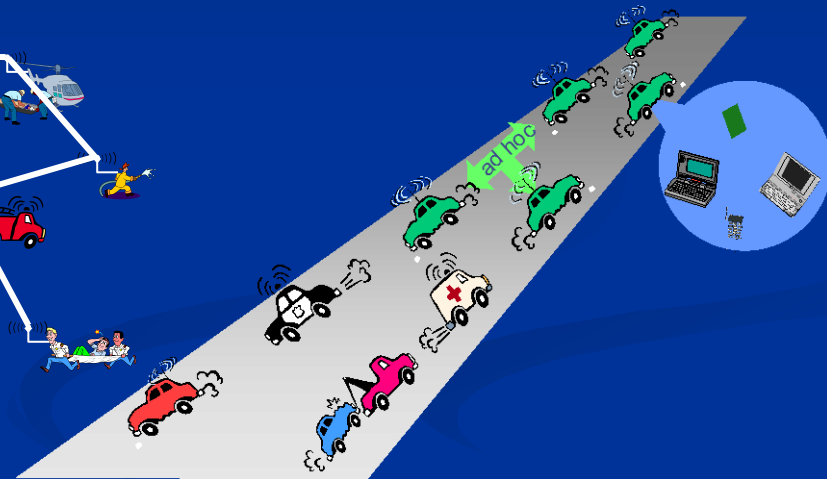
■ Factory floor automation



• Disaster recovery



• Car-to-car communication



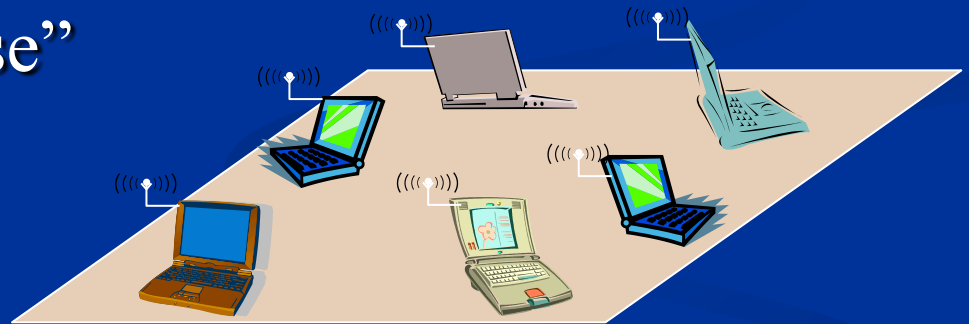
- Military networking: Tanks, soldiers, ...
- Finding out empty parking lots in a city, without asking a server
- Search-and-rescue in an avalanche
- Personal area networking (watch, glasses, PDA, medical appliance, ...)
- ...

Solution: (Wireless) ad hoc networks

- Try to construct a network without infrastructure, using networking abilities of the participants
 - This is an *ad hoc network* – a network constructed “for a special purpose”

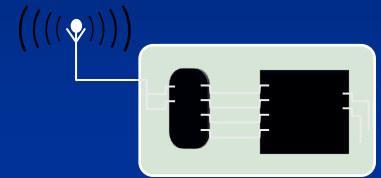
- Simplest example:

Laptops in a conference room –
a *single-hop ad hoc network*



Wireless sensor networks

- Participants in the previous examples were devices close to a human user, interacting with humans



- Alternative concept:

Instead of focusing interaction on humans, focus on interacting with *environment*

- Network is *embedded* in environment
- Nodes in the network are equipped with *sensing* and *actuation* to measure/influence environment
- Nodes process information and communicate it wirelessly

WSN application examples

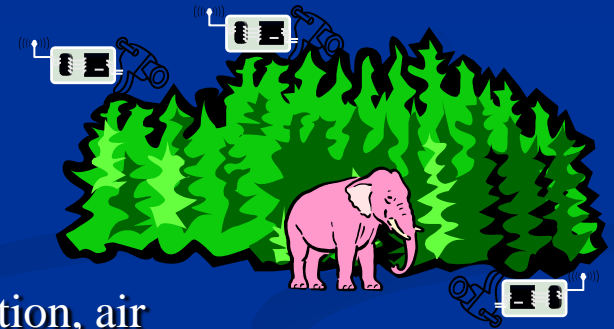
■ Disaster relief operations

- Drop sensor nodes from an aircraft over a wildfire
- Each node measures temperature
- Derive a “temperature map”



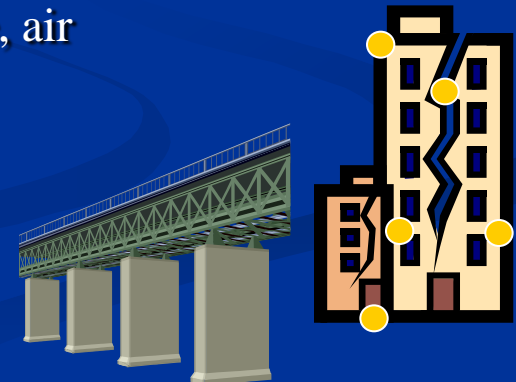
■ Biodiversity mapping

- Use sensor nodes to observe wildlife



■ Intelligent buildings (or bridges)

- Reduce energy wastage by proper humidity, ventilation, air conditioning (HVAC) control
- Needs measurements about room occupancy, temperature, air flow, ...
- Monitor mechanical stress after earthquakes



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Problems/challenges for embedded wireless sensor networks

- Without a central infrastructure, things become much more difficult
- Problems are due to
 - Lack of central entity for organization available
 - Limited range of wireless communication
 - Mobility of participants
 - Battery-operated entities
 - “Quality of service”

No central entity → self-organization

- Without a central entity (like a base station), participants must organize themselves into a network (*self-organization*)
- Pertains to (among others):
 - Medium access control – no base station can assign transmission resources, must be decided in a distributed fashion
 - Finding a route from one participant to another

Limited range

→ multi-hopping

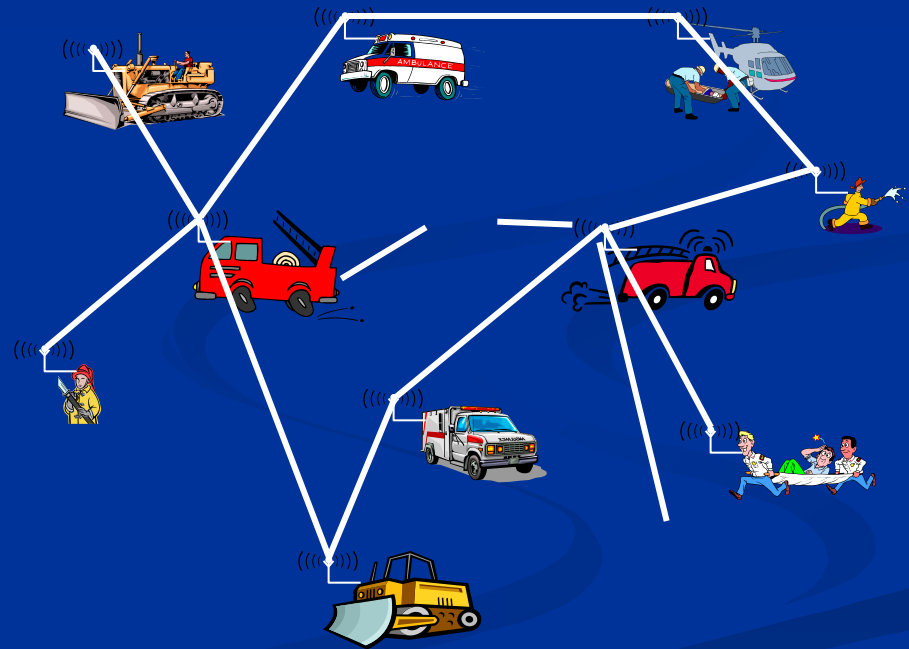
- For many scenarios, communication with peers outside immediate communication range is required
 - Direct communication limited because of distance, obstacles, ...
 - Solution: *multi-hop network*



Mobility

→ Suitable, adaptive protocols

- In many (not all!) ad hoc network applications, participants move around
 - In cellular network: simply hand over to another base station
- In *mobile ad hoc networks (MANET)*:
 - Mobility changes neighborhood relationship
 - Must be compensated for
 - E.g., routes in the network have to be changed
- Complicated by scale
 - Large number of such nodes difficult to support



Battery-operated devices

→ energy-efficient operation

- Often (not always!), participants in an ad hoc network draw energy from batteries
- Desirable: long run time for
 - Individual devices
 - Network as a whole

! Energy-efficient networking protocols

- E.g., use multi-hop routes with low energy consumption (energy/bit)
- E.g., take available battery capacity of devices into account
- How to resolve conflicts between different optimizations?

Quality of service

→ real-time supporting operation

- Traditional QoS metrics do not apply
- Still, service of WSN must be “good”
 - Right answers at the right time

- ! Sensor network protocols with time-constraints supported
- E.g., Consider time constraints of applications when scheduling and planning of systems
 - E.g., Try to reduce communication delay
 - How to resolve conflicts between different optimizations?

What are real-time systems?

- Computing system whose specification includes both logical and temporal correctness requirements
 - *Logical Correctness*: produces correct outputs
 - *Temporal Correctness*: produces outputs at the right time

Real-Time Embedded Systems

Real-time
Embedded sensor
networks

General Purpose
Computing

User's
perspective

Special purpose
computing
Non-
programmable
(Static Tasks)

General purpose

Programmable
(Dynamic Tasks)

Environmental
perspective

Interaction with
physical world

Less Interaction
with physical
world

Real-time
requirements

As fast as
possible

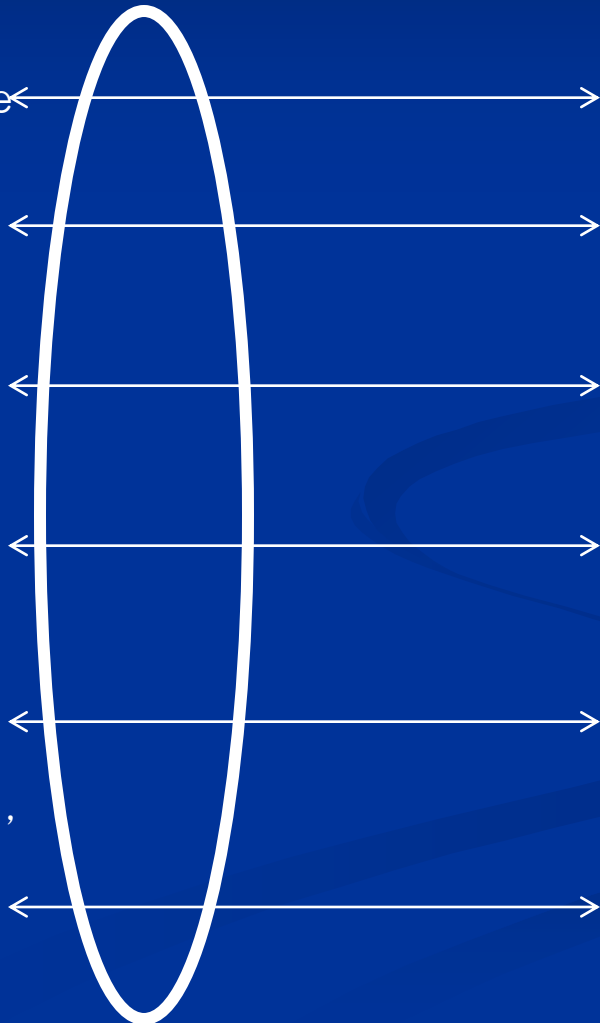
Designer's
perspective

Restricted
resource – small
size, battery, CPU,
memory

Plenty of
resource

Close to
HW– low
level
programming

Far from
HW– high
level
programming



Goals of this talk

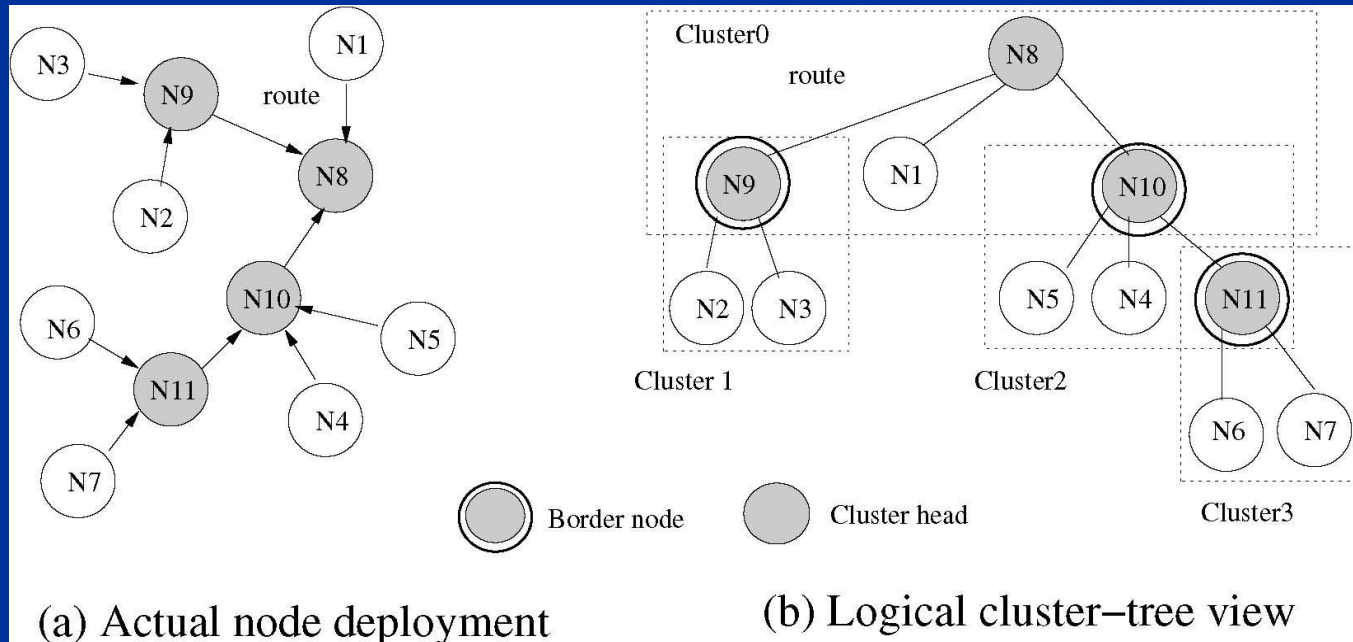
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Assumptions

- Tasks are static and periodic
- Tasks have time constraints
- Sensors are power-limited
- Target platform: cluster-tree ZigBee networks

Cluster-tree ZigBee networks

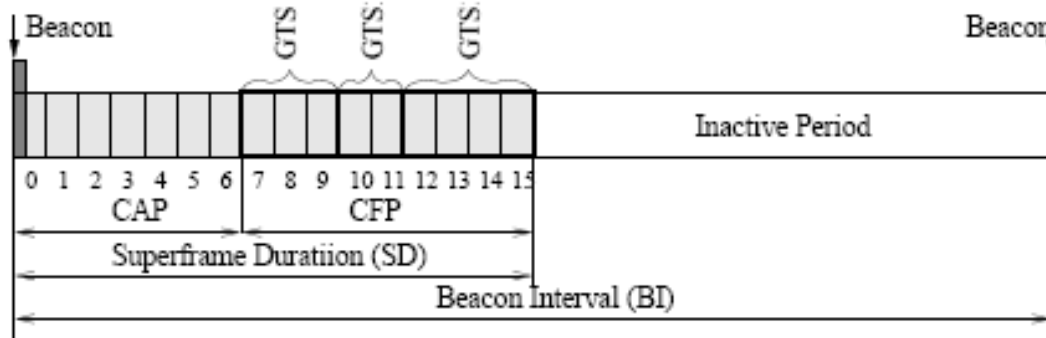
- A ZigBee cluster-tree network is a cost effective choice for sensing and control applications in home and factory environments.
- Consists of multiple clusters
 - Each cluster has a pan coordinator (cluster head), router (border nodes), and ordinary nodes.



Beacon-enabled ZigBee networks

■ For power efficiency...

- Head node broadcasts beacon frames at every *beacon interval* (BI).
- Nodes in a cluster become active only for a portion of each beacon interval, called a *superframe duration* (SD)

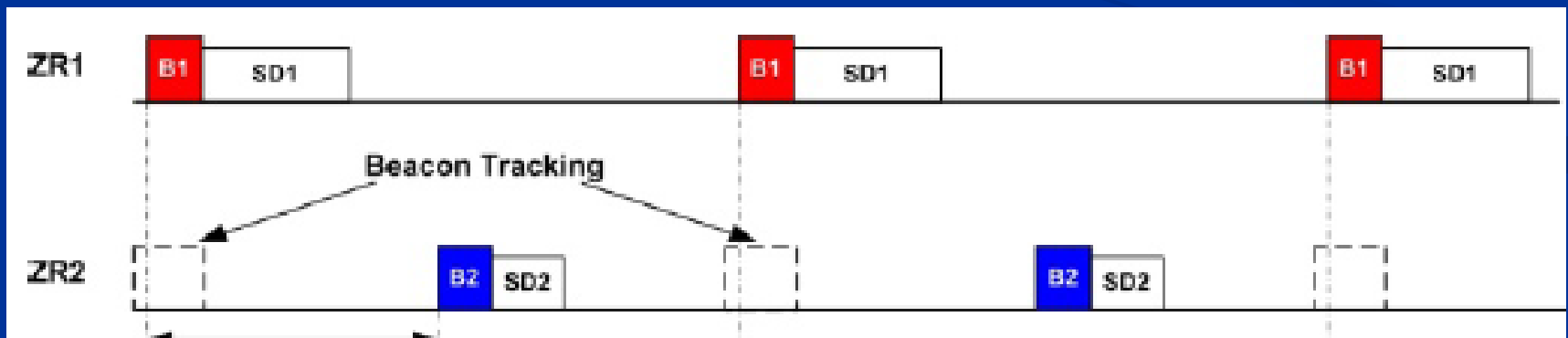


Challenges

- BUT.....Two nodes in different clusters may interfere with each other.
 - To avoid this, *BIs* and *SDs* of multiple clusters need to be carefully configured and scheduled.
 - BI(SD) scheduling algorithm
- Tasks may have time constraints
 - To support this, BI value should be carefully determined
 - BI/SD parameter optimization algorithm
 - To consider this, sensor nodes should be carefully deployed
 - Sensor node deployment algorithm

Challenge 1: Beacon Scheduling Algorithms

- Goal
 - Beacon frames of the different coordinators SHOULD avoid collisions with any other beacon and data frames
- Solution
 - Organize beacon frame transmissions in a serial way
- Ref
 - A. Koubaa, M. Alves, and M. Attia, "Collision-Free Beacon Scheduling Mechanisms for IEEE 802.15.4/Zigbee Cluster-Tree Wireless Sensor Networks," 7th International Workshop on Applications and Services in Wireless Networks (ASWN), 2007.



Challenge 1

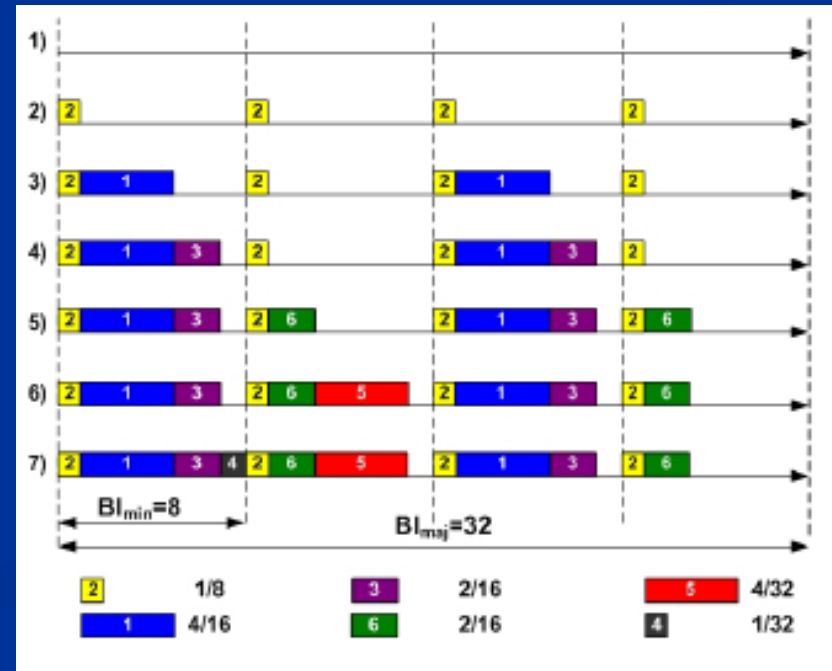
Beacon Scheduling Algorithms

■ Examples

Coordinator	SD	BI
C1	4	16
C2	1	8
C3	2	16
C4	1	32
C5	4	32
C6	2	16

<Table: PAN configuration>

<Scheduled BI and SD>



Challenge 1:

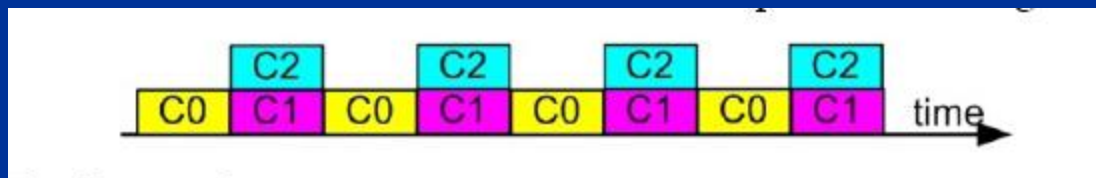
Grouped Beacon Scheduling

■ Extension

- Original algorithm + beacon overlapping
- Increase utilization and feasibility

■ Issues

- Which cluster can be grouped with which?
- How to assign BI and SD for each grouped clusters
- We have worked on this issue



Challenge 1:

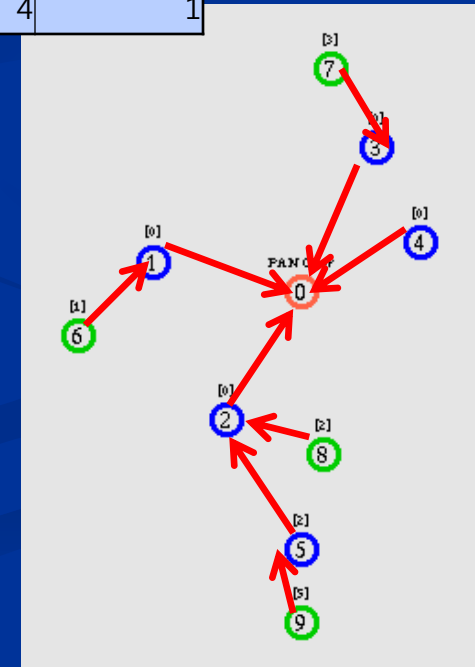
Grouped Beacon Scheduling

■ NS2 Simulation results

- 1 PAN coordinator
- 5 router (cluster heads)
- 4 leaf nodes
- Using NOAH protocol

	BO	SO
PAN	4	2
ZR1	5	2
ZR2	4	1
ZR3	4	1
ZR4	5	0
ZR5	4	1

	Non schedule	Serial SDS	Group SDS
Packet drop rate	16.5%	1.1%	1.2%
Utilization	N/A	71.8%	59%



Challenge 2-1:

GTS-based BI assignment

■ Goal

- guarantee end-to-end deadlines of real-time flows
- maximize the lifetime of the entire system

■ Proposed solution

- *a heuristic algorithm*
- *to optimally configure ZigBee parameters with low complexity by decomposing the global optimization problem into a set of cluster-based local problems.*

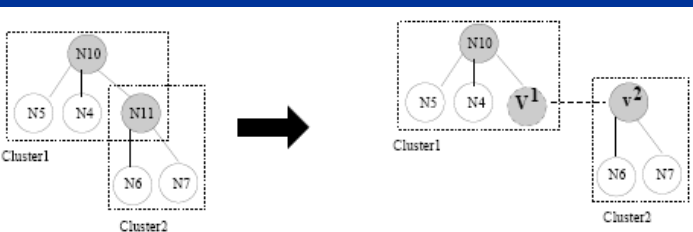
■ Ref

- *Junghee Han, Suhan Choi, and Taejoon Park “Maximizing Lifetime of Cluster-Tree ZigBee Networks Under End-to-End Deadline Constraints”, IEEE Communication Letters, vol14, No3, 2010*

Challenge 2-1: GTS-based BI assignment

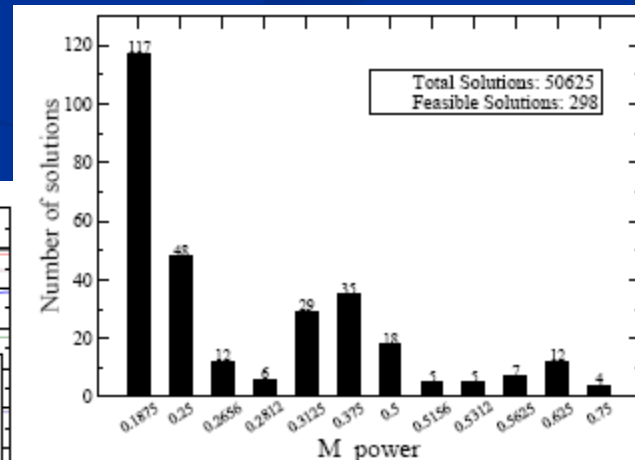
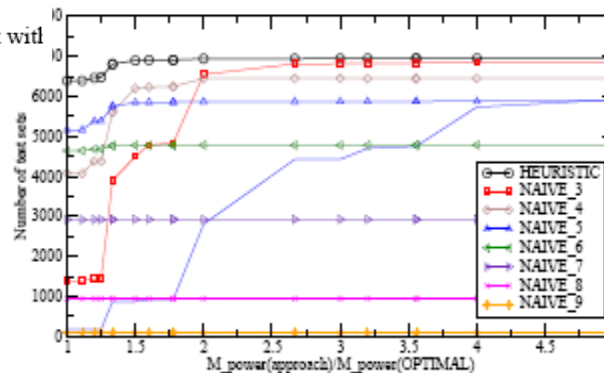
■ Algorithm

1. split a inter-cluster border node belonging to multiple clusters into a set of intra-cluster virtual nodes
2. split end-to-end deadline into a set of cluster-based onehop deadlines
3. estimate a per-cluster worst-case one-hop delay
4. select BI and SD for each cluster based on the above steps



(a) Original ZigBee network

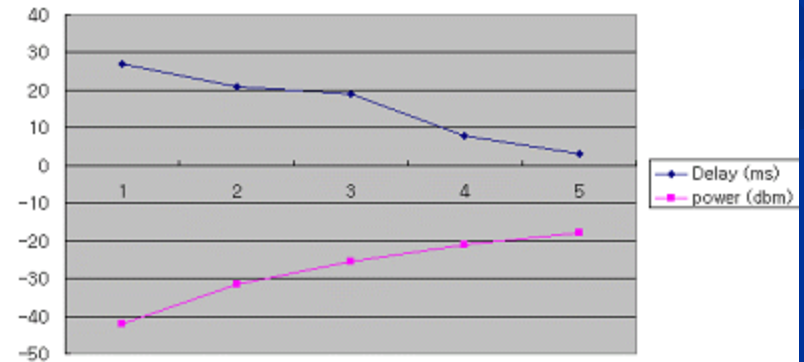
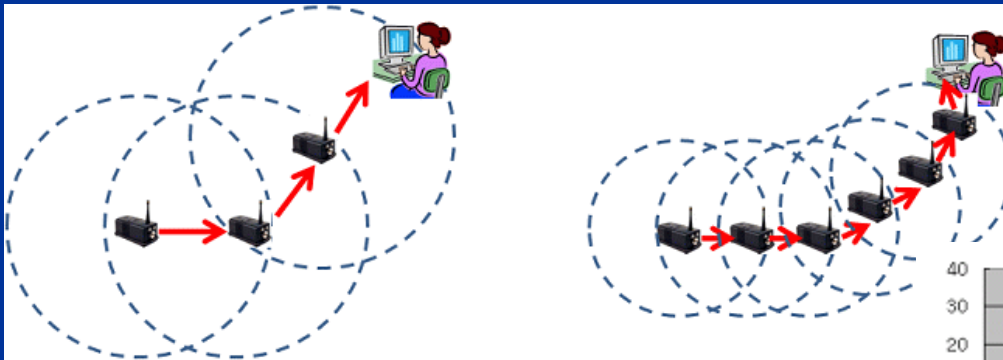
(b) Localized ZigBee network with



Challenge 2-2:

Sensor node deployment

- How to deploy sensor nodes?
 - Goals
 - consider sensor transmission and sensing range
 - guarantee end-to-end deadlines of real-time flows
- Conflicting objectives !!!



Conclusion

- They are just preliminary steps for building scientific foundation of future networks design
- We still have an awful lot of work to do !!!